# Locally homogeneous pseudo-Riemannian manifolds 

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#### Abstract

The work of Cartan, Nomizu, Singer, Tricerri and Vanhecke on manifolds with transitive algebras of Killing vector fields is extended to the pseudo-Riemannian case.


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## 0. Introduction and Summary

The homogeneous universes in space and time "display in simple form features of more complex expanding universes" [19, Ch. 7]. Some of these space-times remain a starting point for studies in general relativity or electromagnetism [ $3,11,13,20$ ]. Equally important in cosmology is the local metric classification of three dimensional geometries viewed as slices in homogeneous spacetimes [8]. Wesson theory [24] and supergravity [17] are other reasons for a geometric study of locally homogeneous pseudo-Riemannian manifolds (l.h.pR.'s). Ref. [7] gives a recent account of the local theory of homogeneous pseudo-Riemannian structures.

Our approach to the study of l.h.pR.'s in their full generality is different, and uses as a starting point the theory of Cartan triples [15]. Since in some respects the extension of that method is obvious, proofs will be kept to a minimum.

Suppose the connected pseudo-Riemannian manifold of index $\nu,(M, g)$ enjoys the following property: there is a Lie algebra ${ }^{f}$ of Killing vector fields on $M$, so that each tangent vector of $M$ extends to an element of $\mathfrak{f}$. Such a pseudo-Riemannian manifold is said locally homogeneous (l.h.pR.) and $\mathfrak{f}$ is a transitive Killing algebra on $M$.

Let $K$ be the abstract group associated with $f$ and let $u$ be an orthoframe at a given point $x$ on $M$. Then one may exponentiate the infinitesimal action of a neighborhood of the identity in $K$ into the orthoframe bundle $O M$ (local version of $I M \subseteq O M$ ). The tangent map defines a monomorphism of $\mathfrak{f}$ to the tangent space at $u$ to $O M$. The structure equations of $\mathscr{f}$ are obtained by pulling back the structure equations of the Ambrose-Singer connection and tautological one-form on the reduced bundle. This gives a decomposition of $\neq$ into $g_{u} \oplus \mathbb{R}^{n}$, where $g_{u}$ (the algebra of the structure group of the reduced bundle) is the $U$-isotropic representation of the isotropy algebra into the pseudo-orthogonal algebra $\mathfrak{o}_{\nu}(n)$. The bracket on $\mathfrak{g}_{u} \oplus \mathbb{R}^{n}$ is a modification of the standard semiproduct with extra terms arising from two operators. One is the Cartan-Singer map $\Gamma_{u}: \mathbb{R}^{n} \rightarrow \mathfrak{p}$, where $\mathfrak{p}$ is a complement of $\mathfrak{g}_{u}$ in $\mathfrak{D}_{\nu}(n)$ (the orthocomplement w.r.t. the Killing form, whenever this exists); it is defined by pulling back the original $\mathfrak{o}_{\nu}(n)$-connection restricted to $\mathfrak{g}_{u}$. The other operator in the definition of the bracket is the curvature at $x$ w.r.t. $u$ of the Ambrose-Singer connection, and is determined by $\Gamma_{u}$ and by $\Omega_{u}$, the $g_{u}$-projection of the curvature along $\mathfrak{p} ;\left(\mathfrak{p}, \Gamma_{u}, \Omega_{u}\right)$ is said to be a $\mathfrak{g}_{u}$-triple.

The l.h.pR. ( $M, g$ ) is locally isometric to a homogeneous space, iff the connected subgroup of Lie algebra $\mathfrak{g}_{u}$ of the abstract Lie group $K$ of Lie algebra $\mathfrak{g}_{u} \oplus \mathbb{R}^{n}$ is closed in $K$. An example of l.h.p.R. which is locally nonisometric to a homogeneous space (see also Refs. [9,10,15,16] ) is displayed in Section 3.

The converse is also true: if $\mathfrak{g}$ is a subalgebra of $\mathfrak{o}_{\nu}(n)$, and $(\mathfrak{p}, \Gamma, \bar{\Omega})$ is a $\mathfrak{g}$ triple, there is a l.h.pR. $(M, g)$, unique up to a local isometry, called the local geometric realization of the $g$-triple, and a frame $u \in O M$, for which $g$ is the linear isotropy algebra w.r.t. $u$; moreover $\Gamma_{u}=\Gamma$ and $\Omega_{u}=\bar{\Omega}$. As such, the problem of listing the $n$-dimensional l.h.pR.'s of index $\nu$ amounts to the following algorithm:
(a) find conjugacy classes of Lie subalgebras of $\mathrm{o}_{\nu}(n)$;
(b) for a given Lie subalgebra $\mathfrak{g}$ of $\mathrm{D}_{\nu}(n)$, find all g -triples.

This method is not too effective if $\mathfrak{g}=0$ (pseudo-Riemannian Lie groups). However, starting from the joint work of Cordero and Parker [6] and using Propositions 3.2 and 3.3 in this study, the program can be carried out completely in dimension three, and even in this low-dimensional case there are examples of l.h.pR.'s that are degenerated (see Section 2 for a definition) or of nonsymmetric Lorentz manifolds, modelled on a symmetric space [5,16]. The + and - spaces which are introduced in Section 3 are typical examples of nonflat Lorentz manifolds with null nongeneric vectors [1].

## 1. Transitive Killing algebras of pseudo-Riemannian manifolds

Assume $g$ is a pseudo-Riemannian structure of index $\nu$ on the $n$-dimensional simply connected manifold $M$ and that $\mathfrak{l}$ is a transitive Killing algebra on ( $M, g$ ). The kernel of the evaluation map $\mathrm{ev}_{x}: \mathfrak{f} \rightarrow T_{x} M$ is the isotropy subalgebra $\mathfrak{f}_{x}$ of $\mathfrak{f}$ at the point $x$.

If $\xi \in \mathfrak{f}_{x}$, the local one-parameter group of isometries generated by $\xi$, $\left(\varphi_{1}^{\xi}\right)$, has the fixed point $x$; consequently, for each $U$ in $O M_{x}$, one has a local one parameter subgroup $\Lambda_{\xi}(t)$ of the pseudo-orthogonal group $\mathrm{O}_{\nu}(n)$ [12], defined as follows:

Let $f: U \rightarrow M$ be a local isometry defined on an open subset $U$ of $M$ and let $L f$ : $O U \rightarrow O M$, be the left of $f$ to the bundle of orthoframes. Then

$$
\left(L \varphi_{t}^{\xi}\right)(u)=u \cdot \Lambda_{\xi}(t)
$$

The linear isotropy representation of $\mathfrak{f}_{x}$ associated with the frame $u$ is $\lambda_{u}$ : $\mathfrak{f}_{x} \rightarrow \mathfrak{o}_{\nu}(n)$,

$$
\begin{equation*}
\lambda_{u}(\xi)=\dot{\Lambda}_{\xi}(0) \tag{1.1}
\end{equation*}
$$

Note that the main difference between the Riemannian and the other $\mathrm{O}_{\nu}(n)$ structures is that $\mathfrak{D}(n)$ is the only compact form among the real forms $\mathfrak{o}_{\alpha}(n)$ of $\mathfrak{v}(n, \mathbb{C})$. Therefore, the method of Cartan triples [15] can be restated in the pseudoRiemannian case whenever the restriction of the Killing form to $\mathfrak{g}_{u}=\lambda_{u}\left(\mathfrak{f}_{x}\right)$ is nondegenerate. A l.h.pR. is nondegenerate (n.l.h.pR.) if it admits at least one transitive Killing algebra $\mathfrak{f}$ with a nondegenerate linear isotropy algebra $\mathfrak{g}_{u}$. Such a $\mathfrak{f}$ is said to be a nonsingular Killing algebra.

Let $(K, H)$ be the pair consisting of the simply connected group of Lie algebra $\mathfrak{f}$, and of its connected Lie subgroup of Lie algebra $\mathfrak{f}_{x}$, and let $\alpha$ be the maximal local $K$-transformation group on $M$ [14] generated by $\mathfrak{f}$.

The map $\alpha$ lifts in a standard way to a local $K$-transformation group of isometries without fixed points $L(\alpha)$ of ( $O M, g_{\nabla}$ ), where $g_{\nabla}$ is the metric associated to the Levi-Civita connection, defined on the basic and fundamental vector fields in the following formulas [22]:

$$
\begin{align*}
& g_{\nabla}\left(B_{u}(X), B_{u}(Y)\right)=\langle X, Y\rangle_{\nu}, \quad X, Y \in \mathbb{R}^{n}, \\
& g_{\nabla}\left(A_{u}^{*}, B_{u}^{*}\right)=-\operatorname{Tr} A B, \quad A, B \in \mathfrak{o}_{\nu}(n) \\
& g_{\nabla}\left(B_{u}(X) \cdot A_{u}^{*}\right)=0, \quad X \in \mathbb{R}^{n}, A \in \mathfrak{o}_{\nu}(n), \tag{1.2}
\end{align*}
$$

where $\langle,\rangle_{\nu}$ is the standard pseudo-Euclidean scalar product of index $\nu$.
Let $D$ be an open neighborhood of $O$ in $\mathfrak{f}$, such that $\varphi_{1}^{\xi}(x)$ is defined for each $\xi \in D$. If $u \in O M_{x}$, one may define the map $J_{u}: \exp D \rightarrow O M$, by

$$
\begin{equation*}
J_{u}(\exp \xi)=L(\alpha)(\exp \xi, u) \tag{1.3}
\end{equation*}
$$

Then, if $\tilde{\xi}$ is the Levi-Civita horizontal lift of $\xi$, and if $A_{\xi}=L_{\xi}-\nabla_{\xi}$, we obtain, as in the Riemannian case:

Proposition 1.1. Let $\left[A_{\xi_{x} x}\right]_{u}$ be the matrix of $A_{\xi_{x}}$ w.r.t. U. Then

$$
\begin{equation*}
\left(d_{1} J_{u}\right)(\xi)=\tilde{\xi}(u)-\left(\left[A_{\xi x}\right]_{u}\right)_{u}^{*} \tag{1.4}
\end{equation*}
$$

Let $\mathfrak{p}$ be a complement of $\mathfrak{g}_{u}$ in $\mathfrak{D}_{\nu}(n)$. From the previous proposition, it follows that $d_{1} J_{u}$ is one to one, so that if $H$ is the horizontal Levi-Civita distribution, and if
$\sigma_{u}: \mathfrak{v}_{\nu}(n) \rightarrow T_{u} O M$ is the $\operatorname{map} A \mapsto A_{u}^{*}$ ' 'tangent'' to the right action of $\mathrm{O}_{\nu}(n)$ in $O M_{u}$, then

$$
\begin{equation*}
\boldsymbol{m}_{u}=\left(d_{1} J_{u}\right)^{-1}\left(\sigma_{u}(\mathfrak{p})+H_{u}\right) \tag{1.5}
\end{equation*}
$$

is a direct summand of $\mathfrak{f}_{x}$ in $\mathfrak{f}$.
As such, the restriction of $\mathrm{ev}_{u}$ to $\mathrm{m}_{u}$ is a linear isomorphism from $\mathrm{m}_{u}$ to $T_{x} M$. Then, if $u=\left(x, u_{1}, \ldots, u_{n}\right)$, for each index $i=1, \ldots, n$, there is a unique $\xi_{i}$ in $m_{u}$, such that $\xi_{i}(x)=u_{i}$. One may prove the following:

Proposition 1.2. Let $\theta \in \mathscr{D}^{1}\left(O M, \mathbb{R}^{n}\right), \omega \in \mathscr{D}^{1}\left(O M, \mathfrak{o}_{\nu}(n)\right)$ be the tautological form and the Levi-Civita connection form on $\exp D$, and let ${ }_{u} \theta=J_{u}^{*} \theta,{ }_{u} \omega=J_{u}^{*} \omega$. Then ${ }_{u} \theta$ and ${ }_{u} \omega$ are left invariant forms on $\exp D$ and $\operatorname{rank}_{u} \theta=n$.

Further, ${ }_{u} \omega$ splits into two vector-valued parts, ${ }_{u} \omega={ }_{u} \omega_{\mathfrak{p}} \oplus_{u} \omega_{\mathrm{g}}$. Let $\|X\|_{\nu}^{2}=\langle X$, $X\rangle_{\nu}$ Then Cartan's theorem on the local structure of a homogeneous Riemannian space [4, Ch. XII] has the following analogue:

Theorem 1.1. (1) There is a linear map $\Gamma_{u}: \mathbb{R}^{n} \rightarrow \mathfrak{p}_{u}$, such that ${ }_{u} \omega_{\mathfrak{p}}=\Gamma_{u}{ }^{\circ}{ }_{u} \theta$.
(2) There is a neighborhood $V$ of $1_{K}$, which is regular for the foliation $F$, given by the system ${ }_{u} \theta=0$. F is a pseudo-Riemannian foliation with the transverse metric $\left\|_{u} \theta\right\|_{\nu}^{2}$ which induces a locally $K$-invariant metric $g_{u}$ on the space of leaves $V / F$.
(3) Let $F_{k}$ be the leaf of $F$ through $k$. The map $F_{k} \rightarrow k(x)$ is a local isometry between $\left(V / F, g_{u}\right)$ and $(M, g)$.

We shall say that $\Gamma_{u}$ is the Cartan-Singer map w.r.t. the decomposition $\mathfrak{D}_{\nu}(n)=g_{u} \oplus \mathfrak{p}$. Let us look for the Maurer-Cartan equations of $\mathfrak{f}$ as a consequence of the structure equations of $O M$.

First, let $\Omega \in \mathfrak{D}^{2}\left(O M, \mathfrak{o}_{\nu}(n)\right)$ be the Riemann curvature form, and let ${ }_{u} \Omega=$ $J_{u}^{*} \Omega .{ }_{u} \Omega$ splits into its $\mathfrak{g}_{u}$ and $\mathfrak{p}$ components:

$$
\begin{equation*}
{ }_{u} \Omega={ }_{u} \Omega_{\mathfrak{g}} \oplus_{u} \Omega_{\mathfrak{p}} \tag{1.6}
\end{equation*}
$$

Let $\left(\epsilon_{b}\right), b=1, \ldots, \frac{1}{2} n(n-1)$, be a basis of $\mathfrak{o}_{\nu}(n)$, such that the first elements lie in $g_{u}$ and the last ones in $\mathfrak{p}$; if $\alpha$ is the index for the elements in $g_{u}$, let ${ }_{u} \Omega_{\mathfrak{g}}$ be the vector-valued form $\frac{1}{2} \Omega_{i j u}^{\alpha} \theta^{i} \wedge_{u} \theta^{j} \epsilon_{\alpha}$.

Since ${ }_{u} \Omega_{i j}^{\alpha}$ are constant on $\exp D$, one may define the bilinear skew symmetric map $\Omega_{n}: \mathbb{R}^{n} \times \mathbb{R}^{n} \rightarrow g_{u}$ by

$$
\begin{equation*}
\Omega_{u}\left(e_{i}, e_{j}\right)={ }_{u} \Omega_{i j}^{\alpha} \epsilon_{\alpha}, \quad i, j=1, \ldots, n \tag{1.7}
\end{equation*}
$$

We call the map $\Omega_{u}$ the $g_{u}$-curvature of $M$, w.r.t. the decomposition $\mathfrak{o}_{\nu}(n)=\mathfrak{g}_{u} \oplus \mathfrak{p}$. Let $T: \mathbb{R}^{n} \times \mathbb{R}^{n} \rightarrow \mathbb{R}^{n}, \bar{\Omega}: \mathbb{R}^{n} \times \mathbb{R}^{n} \rightarrow \mathfrak{g}_{u}$, be defined by

$$
\begin{align*}
& T(X, Y)=\Gamma_{u}(Y) X-\Gamma_{u}(X) Y  \tag{1.8}\\
& \bar{\Omega}(X, Y)=\Omega_{u}(X, Y)-\left[\Gamma_{u}(X), \Gamma_{u}(Y)\right]_{g_{u}} \tag{1.9}
\end{align*}
$$

The bracket in (1.9) is the commutator. The following result is a consequence of the structure equations on $O M$, pulled back on $K$, as in Proposition 1.2.

Theorem 1.2. $f$ is isomorphic to the Lie algebra $\left(g_{u} \oplus \mathbb{R}^{n},[],\right)$ :

$$
\begin{align*}
& {[\xi, \eta]=[\xi, \eta], \quad \forall \xi, \forall \eta \in g_{u}}  \tag{1.10}\\
& {[\xi, X]=\xi(X)+\left[\xi, \Gamma_{u}(X)\right]_{\mathrm{g}_{u}}, \quad \forall \xi \in \mathfrak{g}, \forall X \in \mathbb{R}^{n}}  \tag{1.11}\\
& {[X, Y]=-T(X, Y)-\tilde{\Omega}(X, Y), \quad \forall X, \forall Y \in \mathbb{R}^{n}} \tag{1.12}
\end{align*}
$$

Remark 1.1 If the transitive Killing algebra is nonsingular, we shall always take for $\mathfrak{p}=\mathfrak{p}_{u}$ the orthocomplement of $\mathfrak{g}_{u}$ in $\mathfrak{D}_{\nu}(n)$ w.r.t. the Killing form. In this case, $\mathfrak{m}_{u}=\mathfrak{m}$ does not depend on $u$, and $\mathfrak{f}=\mathcal{f}_{x} \oplus \mathfrak{m}$ is a reductive decomposition. As in the Riemannian case, the canonical connection of the n.l.h.pR. $M$ w.r.t. this decomposition has torsion $T$, and $g_{u}$-part of the curvature $\tilde{\Omega}$. $\Omega_{u}$ is called the $g_{u}$-part of the curvature, and $\Gamma_{u}$ the Cartan-Singer map since the Ambrose-Singer connection refers to the decomposition $\mathfrak{o}_{\nu}(n)=\mathfrak{g}_{u} \oplus \mathfrak{g}_{u}{ }^{1}$.

As a consequence of Theorem 1.2, the Jacobi identities for 1 are as follows:

$$
\begin{align*}
& {[\xi, \tilde{\Omega}(X, Y)]-\tilde{\Omega}(\xi X, Y)-\tilde{\Omega}(X, \xi Y)} \\
& \quad+\left[\left[\xi, \Gamma_{u}(X)\right]_{g_{u}}, \Gamma_{u}(Y)\right]_{\mathrm{g}_{u}}+\left[\xi, \Gamma_{u}(T(X, Y))\right]_{\mathrm{g}_{u}} \\
& \quad+\left[\Gamma_{u}(X),\left[\xi, \Gamma_{u}(Y)\right]_{\mathrm{g}_{u}}\right]_{\mathrm{g}_{u}}=0, \quad \forall \xi \in \mathfrak{g}, \forall X, \forall Y \in \mathbb{R}^{n} ;  \tag{1.13}\\
& \sum_{\text {cycl }} \tilde{\Omega}(T(X, Y), Z)-\left[\tilde{\Omega}(X, Y), \Gamma_{u}(Z)\right]_{\mathrm{g}_{u}}=0 \\
& \quad \forall X, \forall Y, \forall Z \in \mathbb{R}^{n} ;  \tag{1.14}\\
& \sum_{\text {cycl }} \tilde{\Omega}(X, Y)(Z)-T(T(X, Y) Z)=0 \\
& \quad \forall X, \forall Y, \forall Z \in \mathbb{R}^{n} . \tag{1.15}
\end{align*}
$$

The ad $\mathfrak{g}_{u}$-invariance of $\Gamma_{u}$, valid in the Riemannian case, becomes:

$$
\begin{equation*}
\Gamma_{u}(\xi X)=\left[\xi, \Gamma_{u}(X)\right]_{\mathfrak{p}}, \quad \forall \xi \in \mathfrak{g}_{u}, \forall X \in \mathbb{R}^{n} \tag{1.16}
\end{equation*}
$$

The $\mathfrak{p}$-part of the curvature, ${ }_{p} \Omega_{u}$, is given by the same formula as in the Riemannian case:

$$
\begin{equation*}
{ }_{\mathfrak{p}} \Omega_{u}=\left[\Gamma_{u}(X), \Gamma_{u}(Y)\right]_{\mathfrak{p}}+\Gamma_{u}(T(X, Y)) \tag{1.17}
\end{equation*}
$$

The analogue of Theorem 1.3 in Ref. [15] is:
Theorem 1.3. Let $\mathfrak{f}$ be a transitive Killing algebra of the l.h.pR. $M$ and let $\mathfrak{h}$ be the isotropy algebra at point $x$. Then $M$ is locally isometric to a homogeneous pseudoRiemannian space iff $H$ is closed in $K$.

We also have

Proposition 1.3. Let $\mathfrak{f}$ be a nonsingular Killing algebra of $M$. Then the sequence of the covariant derivatives of the Riemannian curvature tensor, $\left(\nabla^{s} R\right)_{s \in \mathbb{N}}$, w.r.t. the frame $u$, may be recovered from the Cartan-Singer map $\Gamma_{u}$ and from the $\mathfrak{g}_{u^{-}}$ curvature $\Omega_{u}$, by means of the formulas:

$$
\begin{align*}
& \hat{\Omega}_{u}=\Omega_{u}+{ }_{p} \Omega_{u}  \tag{1.18}\\
& \left(\nabla^{0} R\right)(X, Y ; Z, T)=\left\langle\hat{\Omega}_{u}\left(u^{-1} X, u^{-1} Y\right) u^{-1} T, u^{-1} Z\right\rangle_{\nu}  \tag{1.19}\\
& \iota_{X} \nabla^{s+1} R=\Gamma_{u}\left(u^{-1} X\right) \cdot \nabla^{s} R \tag{1.20}
\end{align*}
$$

where $\iota_{X}$ is the interior product and $\Gamma_{u}\left(u^{-1} X\right)$ acts as a derivation.

Remark 1.2. The Riemannian curvature tensor of $M$ at $X$ w.r.t. $u$ is given by (1.19) even if $M$ is degenerated.

## 2. 9 -triples

Definition 2.1. Let $g$ be a subalgebra of $\mathfrak{o}_{\nu}(n)$. We say that $(\mathfrak{p}, \Gamma, \bar{\Omega})$ is a $\mathfrak{g}$-triple if $\mathfrak{o}_{\nu}(n)=\mathfrak{g} \oplus \mathfrak{p}, \Gamma: \mathbb{R}^{n} \rightarrow \mathfrak{p}$ is a linear map and $\bar{\Omega}: \mathbb{R}^{n} \times \mathbb{R}^{n} \rightarrow \mathrm{~g}$ is a bilinear antisymmetric map, such that if we formally replace $g$ with $\mathfrak{g}_{u}, \Gamma$ with $\Gamma_{u}$, and $\bar{\Omega}$ with $\Omega_{u}$, then (1.13)-(1.16) will hold true.

If the restriction of the Killing form to g is nondegenerate, we say that the g triple $\left(g^{\perp}, \Gamma, \bar{\Omega}\right)$ is a Cartan triple.

Theorem 2.1. Let $\mathfrak{g}$ be a subalgebra of $\mathrm{D}_{\nu}(n)$, and let $(\mathfrak{p}, \Gamma, \bar{\Omega})$ be a g-triple. Then there is a l.h.pR $(M, g)$ unique up to a local isometry, a frame $u \in O M$, and a transitive Killing algebra $\mathfrak{f}$ on $M$, such that $\lambda_{u}\left(\mathfrak{f}_{\pi(u)}\right)=\mathrm{g}$, and w.r.t. the decomposition $\mathfrak{0}_{\nu}(n)=\mathfrak{g} \oplus \mathfrak{p}, \Gamma_{u}=\Gamma$ and $\Omega_{u}=\bar{\Omega}$.

We shall say that ( $M, g$ ) in Theorem 2.1 is the local geometric realization of the 9 -triple $(\mathfrak{p}, \Gamma, \bar{\Omega})$.

Proof. We consider the Lie algebra $\mathfrak{f}=\left(\mathrm{g} \oplus \mathbb{R}^{n},[],\right)$, where [ , ] is defined in (1.10)-(1.12), with ( $\mathfrak{g}, \mathfrak{p}, \Gamma, \bar{\Omega}$ ) in place of ( $g_{u}, \mathfrak{p}, \Gamma_{u}, \Omega_{n}$ ). It is obvious that $g$ is a Lie subalgebra of $f$. Let $G$ be the connected subgroup with Lie algebra $g$ of the simply connected group $K$, of Lie algebra $\mathfrak{f}$. Let $\theta \oplus \omega \in \mathscr{D}^{1}\left(K, \mathbb{R}^{n} \oplus \mathfrak{g}\right)$ be the canonical form of $K$, and let $V=\exp \Delta \cdot \exp U$, with $\Delta, U$ open neighborhoods of the zeros of $\mathbb{R}^{n}$ and $g$, and $\Delta$ such that through each point of $\exp \Delta$ there passes a unique leaf of the foliation $F$ defined on $V$ by $\theta=0$.

As $\|\theta\|_{\nu}^{2}$ is constant along the leaves of $F$, this tensor field on $V$ is projectable to a pseudo-Riemannian metric $g$ on $M=V / F$.

The tangent space at $x$, the leaf of $1_{K}$, is isomorphic to the quotient $\mathfrak{f} / \mathrm{g}$. We shall consider then the frame $u$ of components $u_{i}=e_{i}+\mathfrak{g}$, which belongs to $O M_{x}$.

Let $\alpha$ be the natural local $K$ transformation group of $M$, defined on some open neighborhood of $1_{K} \times M$ in $K \times M$, induced by the left translation of $K$. We claim that $\alpha$ is almost effective. Suppose it is not. Then there exists a nonzero $\xi \in \mathfrak{g}$ and a sequence $t_{n} \neq 0$, converging to zero, such that $\alpha_{\exp t_{n} \xi}$ is the identity of some neighborhood of the leaf of $1_{K}$ in $M$.

It follows that there exists a neighborhood $N$ of $0 \in \mathbb{R}^{n}$, such that for each $X \in N$, there is some $\eta_{n} \in \mathfrak{g}$, such that $\exp t_{n} \xi \cdot \exp X=\exp X \cdot \exp \eta_{n}$. This condition expresses the fact that we remain on the same leaf of $F$, as we act by $\exp t_{n} \xi=\mathrm{id}$. Then due to a consequence of the Campbell-Hausdorff formula [21, Th. 5.16], if we change $X$ in the above formula to $t_{n} X$, we deduce that $t_{n}^{2}[\xi, X]+\mathrm{o}\left(t_{n}^{3}\right)=-t_{n} \xi+\eta_{n} \in g$.

Then $[\xi, X]$ is in $\mathfrak{g}$, as a limit of elements in $\mathfrak{g}$, and ad $\xi\left(\mathbb{R}^{n}\right) \subseteq \mathfrak{g}$. From (1.11), this is possible iff $\xi=0$, thereby proving our claim and showing that $\lambda_{u}\left(\mathfrak{f}_{x}\right)=\mathfrak{g}$.

Further, since the Lie algebras $\mathfrak{f}$ and $\mathfrak{f}_{u}$ associated to the $\mathfrak{g}$-triples $(\mathfrak{p}, \Gamma, \bar{\Omega})$ and ( $\mathfrak{p}_{u}, \Gamma_{u}, \Omega_{u}$ ) have the same structure equations, $\Gamma=\Gamma_{u}$ and $\bar{\Omega}=\Omega_{u}$.

Let $K$ be the simply connected Lie group of Lie algebra $\mathfrak{f}=\left(\mathfrak{g} \oplus \mathbb{R}^{n},[],\right)$, associated to the $\mathfrak{g}$-triple ( $\mathfrak{p}, \Gamma, \bar{\Omega}$ ), and let $G$ be the connected subgroup of $K$, of Lie algebra $\mathfrak{g}$. If $G$ is closed in $K$, then, as in the proof of Theorem 1.4., $\|\theta\|_{\nu}^{2}$ is projectable to a pseudo-Riemannian metric $g$ on $K / G$. We shall say that ( $K / G$, $g)$ is the geometric realization of the closed $\mathfrak{g}$-triple $(\mathfrak{p}, \Gamma, \bar{\Omega})$.

The geometric realization of a $\mathfrak{g}$-triple is simply connected; moreover, if $\mathfrak{f}$ has an $n$-dimensional subalgebra $\mathfrak{l}$, which is transverse to $\mathfrak{g}$, then the geometric realization is diffeomorphic to the simply connected group of Lie algebra $l$.

Until now, there were no relevant differences between the Riemannian and the pseudo-Riemannian case. However, if we try to generalize the equivalence criterion of section 3 in Ref. [15], we encounter some difficulties even for n.l.h.pR.'s, since the nondegeneracy of a transitive Killing algebra may not be inherited from the whole Lie algebra of Killing vector fields on $M, \mathfrak{f}(M)$. All we can prove is the following:

Theorem 2.2. Let $M_{1}, M_{2}$ be two l.h.pR.'s. Then there is a local isometry from $M_{1}$ to $M_{2}$, iff there are some frames $u_{1} \in O M_{1}, u_{2} \in O M_{2}$, such that $\lambda_{u_{1}}\left(\mathfrak{f}\left(M_{1}\right)_{m u_{1}}\right)=\lambda_{u_{2}}\left(\mathfrak{f}\left(M_{2}\right)_{m u_{2}}\right)=\mathfrak{g}$ and there is a complement $\mathfrak{p}$ of $\mathfrak{g}$ in $\mathfrak{0}_{\nu}(n)$, so that w.r.t. the decomposition $\mathfrak{0}_{\nu}(n)=\mathfrak{g} \oplus \mathfrak{p}$, the Cartan-Singer maps and the g -parts of the curvature of $M_{1}$ and $M_{2}$ are equal.

For $\alpha=1,2$, let $\mathfrak{f}_{\alpha}$ be a transitive Killing algebra of some $n$-dimensional 1.h.pR. $M_{\alpha}$ of index $\nu$, and let $u_{\alpha} \in O M_{\alpha}$.

Corollary 2.1. If $M_{1}$ is locally isometric to $M_{2}$, their curvature tensors $R_{1, u_{1}}$, $R_{2, u_{2}}$, given by (1.19), are conjugate under the natural action of $O_{\nu}(n)$ on the space of curvature tensors.

If $\mathfrak{f}$ is a transitive Killing algebra of $M, u \in O M_{x}$ and $\hat{\Omega}_{u}$ is defined in (1.18), the Ricci form associated with ( $\mathfrak{f}, u$ ) is the bilinear symmetric form ${ }_{\mu} \rho$ : $\mathbb{R}^{n} \times \mathbb{R}^{n} \rightarrow \mathbb{R}$, given by:

$$
\begin{equation*}
{ }_{u} \rho\left(e_{i}, e_{j}\right)=\operatorname{Tr}\left(x \rightarrow \hat{\Omega}_{u}\left(x, e_{i}\right) e_{j}\right) . \tag{2.1}
\end{equation*}
$$

The Ricci polynomial Ric is defined by:

$$
\begin{equation*}
\operatorname{Ric}(t)=\operatorname{det}\left({ }_{u} \rho\left(e_{i}, e_{j}\right)-t_{\nu} \delta_{i j}\right), \tag{2.2}
\end{equation*}
$$

where ${ }_{\nu} \delta_{i j}=\delta_{i j}$ for $i \leqslant n-\nu$ and ${ }_{\nu} \delta_{i j}=-\delta_{i j}$ for $i>n-\nu$.
Remark 2.1. $\operatorname{Ric}(t)$ is an invariant of the local isometry class of the 1.h.pR. ( $M$, g).

Remark 2.2. If $\mathfrak{f}$ is a nonsingular Killing algebra of ( $M, g$ ), and if $\mathfrak{g}=\lambda_{u}\left(\mathcal{f}_{x}\right)$, then, as in the Riemannian case, one may find $\lambda_{u}\left(\tilde{f}(M)_{x}\right)$, starting from the Cartan triple ( $\mathrm{g}^{\perp}, \Gamma_{u}, \bar{\Omega}_{u}$ ), as follows:

$$
\lambda_{u}\left(\mathscr{f}(M)_{x}\right)=\left\{\xi \in \mathfrak{o}_{\nu}(n), \xi \cdot \nabla^{s} R=0, \forall s \in \mathbb{N}\right\} .
$$

In this case, one may label as $\mathrm{g}_{s}$ the vector subspace $\left\{\xi \in \mathfrak{o}_{\nu}(n), \xi \cdot \nabla^{p} R=0\right.$, $p \leqslant s\}$ of $\mathfrak{0}_{\nu}(n)$, and define the Singer invariant to be the largest $s$, such that $\mathrm{g}_{s} \neq \mathrm{g}_{\infty}$.

## 3. Examples

This section provides applications of the mechanics of $\mathfrak{g}$-triples. A first example proves the consistency of Theorem 1.3.

In order to obtain examples relevant to that theorem, it is natural to look for a transitive Killing algebra, whose linear isotropy subalgebra is the Lie algebra of a nonclosed Lie subgroup of $\mathrm{O}_{\nu}(n)$.

As a vector space, $\mathfrak{o}_{\nu}(n)$ has the basis $\left(f_{i}^{j}\right)_{1 \leqslant i<j \leqslant n}$,

$$
\begin{equation*}
f_{i}^{j}=E_{i}^{j}-{ }_{\nu} \delta_{i j} E_{j}^{i} . \tag{3.1}
\end{equation*}
$$

In our example $n=5$ and $\nu=3$, and we start from the maximal toral subalgebra $\mathrm{t}=\mathbb{R} f_{1}^{2} \oplus \mathbb{R} f_{3}^{4}$ of $\mathrm{D}_{3}(5)$, tangent to the torus $T$.

Let $r$ be a positive irrational number. Then, the one-parameter subgroup $G_{r}$ of the Lie algebra $g_{r}=\mathbb{R}\left(f_{1}^{2}+f_{3}^{4}\right)$ is dense in $T$, and therefore we will look for a Cartan triple ( $\mathfrak{g}, \Gamma, \bar{\Omega}$ ) with $\mathfrak{g}=\mathrm{g}_{r}$. Let $f=f_{1}^{2}+f_{3}^{4}$.

One of the solutions for (1.16)-(1.18) is

$$
\begin{align*}
& \Gamma\left(e_{1}\right)=b f_{2}^{5}, \quad \Gamma\left(e_{2}\right)=-b f_{1}^{5}, \quad \Gamma\left(e_{3}\right)=d f_{4}^{5} \\
& \Gamma\left(e_{4}\right)=-d f_{3}^{5}, \quad \Gamma\left(e_{5}\right)=0 \\
& \bar{\Omega}\left(e_{1}, e_{2}\right)=b\left(\frac{b}{1+r^{2}}+\frac{2 d}{r}\right) f \\
& \bar{\Omega}\left(e_{3}, e_{4}\right)=-d\left(\frac{r d}{1+r^{2}}+2 b\right) f, \quad b>0, d>0, b r-d<0 \tag{3.2}
\end{align*}
$$

The corresponding transitive Killing algebra $\mathfrak{f}=\left(g \oplus \mathbb{R}^{5},[],\right)$ splits as a direct sum of two copies of $\mathfrak{\mathfrak { u }}(2), \mathfrak{f}=\mathfrak{f}_{1} \oplus \mathfrak{f}_{2}$, where $\mathfrak{f}_{1}=\operatorname{Span}\left(e_{1}, e_{2}, r e_{5}-d f\right)$, $\mathfrak{f}_{2}=\operatorname{Span}\left(e_{3}, e_{4},-e_{5}+b f\right)$.

The subalgebra $\mathfrak{F}=\mathbb{R}\left(-e_{5}+b f\right) \oplus \mathbb{R}\left(r e_{5}-d f\right)$ is toral in $\mathfrak{l}$. The Lie subgroup of $H$ of the Lie algebra $g$, of the simply connected group $K=S U(2) \times \operatorname{SU}(2)$ of the Lie algebra $\mathfrak{f}$, is dense in the torus $S$ of the Lie algebra $\mathfrak{3}$.

Theorem 3.1. For any positive irrational $r$, the local geometric realization of the Cartan triple $\left(g_{n}, \Gamma, \bar{\Omega}\right)$, defined in (3.2), is a five-dimensional n.l.h.pR. of index 3, that is not locally isometric to a homogeneous space.

Remark 3.1. (See Ref. [23] for a Riemannian analogue.) A local geometric realization of the Cartan triple (3.2) may be viewed as a transverse manifold $M$ to the pseudo-Riemannian foliation $D_{r}$ of $S U(2) \times S U(2)$, with the left invariant metric $g$ defined by the ad $\mathfrak{h}$-invariant bilinear form $B$ on $\mathfrak{S u}(2), B\left(\left(x_{1}, y_{1}\right),\left(x_{2}\right.\right.$, $\left.\left.y_{2}\right)\right)=-\lambda \operatorname{Tr}\left(x_{1}, y_{1}\right)+\mu \operatorname{Tr}\left(x_{2}, y_{2}\right)$,

$$
\lambda=\frac{r}{b(d-b r)}, \quad \mu=\frac{1}{d(d-b r)}
$$

$D_{r}$ is the Lie foliation generated by the diagonal matrices

$$
\left(\begin{array}{llll}
\mathrm{e}^{\mathrm{i} t} & & & \\
& \mathrm{e}^{-\mathrm{i} t} & & \\
& & \mathrm{e}^{\mathrm{i} r t} & \\
& & & \mathrm{e}^{-\mathrm{i} r t}
\end{array}\right)
$$

and the factor metric $g$.
Our next objective is to find the three-dimensional degenerate l.h.pR.'s. Let us denote $f_{1}^{2}+f_{1}^{3}$ by $f$. In order to exhaust all the possibilities, we need the following elementary fact:

Lemma 3.1. A degenerate Lie subalgebra of $\mathfrak{o}_{1}(3)$ is conjugate to $m(3)=\operatorname{Span}(f$, $f_{2}^{3}$ ) or to $\mathfrak{h} t=\mathbb{R} f$.

It may be shown that the local geometric realization of an $\mathfrak{m}(3)$-triple has constant negative curvature.

If one identifies $\mathfrak{D}_{1}(3)$ with the Lie algebra of the full group of isometries of the hyperbolic plane, $\mathfrak{h t}$ is the Lie algebra of the horocyclic translations [6, p. 3].

We list the $\mathfrak{h t}$-triples. Since the Killing form vanishes along $\mathfrak{h t}$, we shall take for its complement in $\mathfrak{D}_{1}(3)$, the plane $\mathfrak{p}=\operatorname{Span}\left(f_{1}^{3}, f_{2}^{3}\right)$.
Any $\mathfrak{h t}$-triple of the form ( $\mathfrak{p}, \Gamma, \bar{\Omega}$ ) is given by

$$
\begin{equation*}
\Gamma\left(e_{1}\right)=a f_{2}^{3}, \quad \Gamma\left(e_{2}\right)=\Gamma\left(e_{3}\right)=-a f_{1}^{3}+b f_{2}^{3}, \quad \bar{\Omega}\left(e_{i}, e_{j}\right)=\Omega_{i j} f, \tag{3.3}
\end{equation*}
$$

where

$$
\begin{equation*}
\Omega_{12}-\Omega_{13}+a^{2}=0, \quad \Omega_{23}=a b=0 . \tag{3.4}
\end{equation*}
$$

From (1.9) it follows that:

$$
\begin{equation*}
\tilde{\Omega}\left(e_{1}, e_{2}\right)=\tilde{\Omega}_{12} f, \quad \tilde{\Omega}\left(e_{1}, e_{3}\right)=\tilde{\Omega}_{13} f, \quad \tilde{\Omega}\left(e_{2}, e_{3}\right)=\Omega_{23} f \tag{3.5}
\end{equation*}
$$

If $a \neq 0$, the transitive Killing algebra associated to the $\mathfrak{b t}$-triple $(\mathfrak{p}, \Gamma, \bar{\Omega})$, $\mathfrak{f}=\mathfrak{h t} \oplus \operatorname{Span}\left(e_{1}, e_{2}, e_{3}\right)$, has the structure equations

$$
\begin{align*}
& {\left[e_{1}, e_{2}\right]=2 a e_{3}+\left(a^{2}-\Omega_{12}\right) f, \quad\left[e_{1}, e_{3}\right]=a\left(e_{2}+a_{3}\right)-\Omega_{12} f,} \\
& {\left[e_{2}, e_{3}\right]=-a e_{1}, \quad\left[f, e_{1}\right]=e_{3}-e_{2}+a f, \quad\left[f, e_{2}\right]=\left[f, e_{3}\right]=e_{1} .} \tag{3.6}
\end{align*}
$$

By (1.17) and (1.18) the curvature of the local geometric realization is

$$
\begin{align*}
& \hat{\Omega}\left(e_{1}, e_{2}\right)=\Omega_{12} f_{1}^{2}+\left(\Omega_{12}+a^{2}\right) f_{1}^{3}, \quad \hat{\Omega}\left(e_{2}, e_{3}\right)=a^{2} f_{2}^{3}, \\
& \hat{\Omega}\left(e_{1}, e_{3}\right)=\left(\Omega_{12}+a^{2}\right) f_{1}^{2}+\left(\Omega_{12}+2 a^{2}\right) f_{1}^{3}, \tag{3.7}
\end{align*}
$$

with the Ricci polynomial

$$
\begin{equation*}
\operatorname{Ric}(t)=\left(t+2 a^{2}\right)^{3} . \tag{3.8}
\end{equation*}
$$

Proposition 3.1. There exist a locally homogeneous Lorentz manifold (l.h.L.) which has the Ricci polynomial of a space of constant negative curvature, but is not of constant negative curvature.

Proof. This is a three-dimensional l.h.pR. which apparently is not dependent only on the Ricci polynomial.
From (3.7), it follows that the local geometric realization $M$ of a $\mathfrak{h t}$-triple ( $\mathfrak{p}$, $\Gamma, \bar{\Omega}$ ) with $a \neq 0$ has the possible nonzero components of the curvature tensor given by

$$
R_{1212}=\Omega_{12}, \quad R_{1213}=\Omega_{12}+a^{2}, \quad R_{1313}=\Omega_{12}+2 a^{2}, \quad R_{2323}=a^{2} .
$$

Let $\left[x_{1}, x_{2}, x_{3}\right]$ be the dual (plückerian) coordinates of some nondegenerate tangent plane $\pi \in G_{2}\left(T_{x} M\right)$, w.r.t. $U$, the orthoframe given by Theorem 2.1. The sectional curvature of $\pi$ is (see Ref. [2]):

$$
\begin{equation*}
K_{x}\left[x_{1}, x_{2}, x_{3}\right]=-a^{2}+\left(\Omega_{12}+a^{2}\right) \frac{\left(x_{2}-x_{3}\right)^{2}}{x_{3}^{2}-x_{1}^{2}-x_{2}^{2}} \tag{3.9}
\end{equation*}
$$

showing that the space has constant curvature iff $\Omega_{12}+a^{2}=0$.
Thus, $K_{x}$ is a rational function defined on the complement of the oval $x_{3}^{2}-$ $x_{1}^{2}-x_{2}^{2}=0$ (the null locus) in $\mathbb{P}^{2} \mathbb{R}$, whose image is the union of two connected subsets $I_{t}, I_{s}$, of $\mathbb{R}$, corresponding to the timelike and the spacelike planes, respectively. The conic $Q=0$ is the homaloidal conic of the point $x$. Of course, $I_{t}$ and $I_{s}$ are invariant under local isometries, and therefore they are local invariants of a 1.h.L.

If $\Omega_{12}+a^{2}>0, I_{t}=\left[-a^{2}, \infty\right)$, and if $\Omega_{12}+a^{2}<0$ then, $I_{t}=\left(-\infty,-a^{2}\right]$, which proves that there are at least three pairwise nonisometric l.h.L.'s, having the Ricci polynomial of a space of constant negative curvature.

If $a=0, \mathfrak{f}=\mathfrak{h} t \oplus \operatorname{Span}\left(e_{1}, e_{2}, e_{3}\right)$ has the structure equations

$$
\begin{align*}
& {\left[e_{1}, e_{2}\right]=\left[e_{1}, e_{3}\right]=-\Omega_{12} f, \quad\left[e_{2}, e_{3}\right]=-b\left(e_{3}-e_{2}\right),} \\
& {\left[f, e_{1}\right]=e_{3}-e_{2}, \quad\left[f, e_{2}\right]=\left[f, e_{3}\right]=e_{1}+b f .} \tag{3.10}
\end{align*}
$$

For $b=0, \mathfrak{t}=\mathfrak{h} \oplus \operatorname{Span}\left(e_{1}, e_{2}, e_{3}\right)$ is a reductive decomposition, such that the geometric realization is a Lorentz symmetric space that is indecomposable and does not have constant curvature if $\Omega_{12} \neq 0$; this is immediate, since the Ricci polynomial is $t^{3}$ and the curvature is not zero.

Let $K$ be the simply connected group of Lie algebra $f$. The connected Lie subgroup of the Lie algebra $\mathfrak{h t}$ is closed in $K$. We shall now that that there are precisely three distinct geometric realizations of this type.

Indeed, the homoloidal conic is the double line $\left(x_{2}-x_{3}\right)^{2}=0$, tangent to the null locus, and the sectional curvature is given by (3.9), where $a=0$. Then, if $\omega \beta<0$, and $M, M^{\prime}$ are two local geometric realizations that are associated with the parameters $\Omega_{12}=\omega$ and $\Omega_{12}=\beta$, respectively, one may assume, w.l.o.g., that $I_{t}(M)=[0, \infty)$ and $I_{t}\left(M^{\prime}\right)=(-\infty, 0]$, and therefore $M$ and $M^{\prime}$ are not locally isometric. We shall say that the geometric realization of an $\mathfrak{h t}$-triple with $a=0$ is $\mathrm{a}+$ space, if $\Omega_{12}>0$, and is a - space is $\Omega_{12}<0$.

It is known that a Riemannian manifold modelled on an irreducible symmetric space is locally symmetric [5]. The Lorentzian analogue of this statement fails to be true:

Proposition 3.2. Let $\alpha$ be a real root of $\alpha^{2}-\alpha b+\Omega_{12}=0$. Let Sol(b, $\alpha$ ) be the Lie group of affinities of the real plane, generated by the translations $x^{\prime}=x+u$, $y^{\prime}=y+v$, and by the dilations $x^{\prime}=\exp (t) x, y^{\prime}=\exp (b t / \alpha) y$, together with the Lorentz metric

$$
\begin{equation*}
g=\exp (2 t) \cdot \mathrm{d} u^{2}+\frac{1}{\alpha^{2}}\left(2 \exp (b t / \alpha) \mathrm{d} t \cdot \mathrm{~d} v-\mathrm{d} t^{2}\right) \tag{3.11}
\end{equation*}
$$

If $b \Omega_{12} \neq 0$, then $\operatorname{Sol}(\mathrm{b}, \alpha)$ is modelled on a symmetric space, without being locally symmetric.

Proof. If $\Omega_{12} \neq 0$, the geometric realization of the $\mathfrak{h t}$-triple ( $\mathfrak{p}, \Gamma, \bar{\Omega}$ ), defined by (3.3)-(3.5), with $a=0 \neq \Omega_{12}$, has $\mathfrak{f}=\mathfrak{h} \mathfrak{t} \oplus \operatorname{Span}\left(e_{1}, e_{2}, e_{3}\right)$ as maximal Killing algebra. For a fixed $\Omega_{12}$, all these spaces have the same curvature tensor w.r.t. the frame ( $e_{1}, e_{2}, e_{3}$ ). We are looking for a Lorentz Lie group structure on such a space. Supposing $e_{1}^{\prime}, e_{2}^{\prime}, e_{3}^{\prime}$, with $e_{i}^{\prime}=e_{i}+\alpha_{i} f$, generate a subalgebra of $\mathfrak{f}$. From (3.10) it follows that such a subalgebra exists iff $b^{2}-4 \Omega_{12}>0$, and in this case $\alpha_{1}$ is a solution of $\alpha^{2}-\alpha b+\Omega_{12}=0$ and $\alpha_{2}=\alpha_{3}$. Assume for simplicity that $\alpha_{3}=0$. The Lie subalgebra $\mathfrak{l}=\operatorname{Span}\left(e_{1}^{\prime}, e_{2}^{\prime}, e_{3}^{\prime}\right)$ is solvable and centreless,

$$
\left[e_{1}^{\prime}, e_{2}^{\prime}\right]=\left[e_{1}^{\prime}, e_{3}^{\prime}\right]=\alpha e_{1}^{\prime}, \quad\left[e_{2}^{\prime}, e_{3}^{\prime}\right]=b\left(e_{2}^{\prime}-e_{3}^{\prime}\right)
$$

and then the canonical form $\theta=\theta^{i} e_{i}^{\prime}$ of $L$, the simply connected Lie group of Lie algebra $\mathfrak{l}$, satisfies the system

$$
\mathrm{d} \theta^{1}+\alpha \theta^{1} \wedge\left(\theta^{2}+\theta^{3}\right)=0, \quad \mathrm{~d} \theta^{2}+b \theta^{2} \wedge \theta^{3}=0, \quad \mathrm{~d}\left(\theta^{2}+\theta^{3}\right)=0
$$

$L$ is the geometric realization of our $\mathfrak{h t}$-triple, and then $e^{\prime}=\left(e_{1}^{\prime}, e_{2}^{\prime}, e_{3}^{\prime}\right)$ is a field of orthoframes of $L$. A straightforward calculation shows that $\left(\nabla_{e_{2}} R\right)\left(e_{1}^{\prime}, e_{2}^{\prime}, e_{1}^{\prime}\right.$, $\left.e_{3}^{\prime}\right)=-2 b \Omega_{12} \neq 0$, showing that $L$ is not a symmetric space.

Since $\mathfrak{l}$ is centreless it is isomorphic to its adjoint representation. Let

$$
X_{1}=\operatorname{ad} e_{1}^{\prime}, X_{2}=\operatorname{ad} \frac{1}{\alpha}\left(e_{2}^{\prime}-e_{3}^{\prime}\right), X_{3}=\operatorname{ad} \frac{1}{\alpha} e_{3}^{\prime}
$$

and let $A=\exp \left(u X_{1}\right) \exp \left(\nu X_{2}\right) \exp \left(t X_{3}\right)$ be an arbitrary element in the Lie subgroup of $G I(3, \mathbb{R})$ generated by ad $\mathfrak{l}$. Then the canonical form $\Theta=A^{-1} d A$ is easily seen to be

$$
\exp (t) \mathrm{d} u X_{1}+\exp (b t / \alpha) \mathrm{d} v X_{2}+\mathrm{d} t X_{3}=\operatorname{ad}(\theta)
$$

and we identify $\left(\operatorname{Ad}(L),\|\theta\|_{1}^{2}\right)$ with $\operatorname{Sol}(\mathrm{b}, \alpha)$.
Proposition 3.3. Suppose $\beta \neq 0$ is the imaginary part of a complex root of the equation $z^{2}-b z+\Omega_{12}=0$. Then $D(b, \beta)=\left(\mathbb{R}^{3}, g\right)$ where $g$ is given by

$$
\begin{equation*}
g=\exp (b x)\left(\cos ^{2} \beta x \cdot(\mathrm{~d} y)^{2}+2 \mathrm{~d} x \cdot \mathrm{~d} t\right)-(\mathrm{d} x)^{2} \tag{3.12}
\end{equation*}
$$

is a degenerate l.h.pR.Any three-dimensional degenerate l.h.pR. is locally isometric to some $D(b, \beta)$.

Proof. Take an $\mathfrak{h t}$ triple ( $\mathfrak{p}, \Gamma, \bar{\Omega}$ ), defined by (3.3)-(3.5) with $a=0<\Omega_{12}$, $b^{2}-4 \Omega_{12}<0$. As in the proof of Proposition 3.2, $=\mathbb{R} f \oplus \operatorname{Span}\left(e_{1}, e_{2}, e_{3}\right)$ is the
maximal Killing algebra of the geometric realization of ( $\mathfrak{p}, \Gamma, \bar{\Omega}$ ). The Lie algebra $\mathfrak{f}$ has no subalgebra transverse to $\mathfrak{h t}$, and $\mathfrak{h t}$ is degenerate w.r.t. the Killing form. To end the proof, it is enough to show that the geometric realization of this $\mathfrak{g t}$ triple is $D(b, \beta)$.

We claim that the geometric realization is diffeomorphic to $\mathbb{R}^{3}$.
Our $\mathfrak{h t}$-triple is closed, since $\mathfrak{f}$ is solvable. Let $\mathfrak{g}$ be the derived algebra of $\mathfrak{f}$; this is the three-dimensional nilpotent Lie algebra. Let $K$ be the simply connected group of Lie algebra $f$, and let $G$ be the subgroup of Lie algebra $g$ and $H=\exp (\mathbb{R} f)$.

Since $G$ is a codimension 1 Lie subgroup of the solvable group $K, K / G$ is $\mathbb{R}$, and since $G$ is $N i l, G / H$ is easily seen to be $\mathbb{R}^{2}$. The projections defining these quotients being trivial fibrations, let $k: \mathbb{R} \rightarrow K, g: \mathbb{R}^{2} \rightarrow G$ be differentiable sections of these fibrations. Then the map $(a, b, c) \rightarrow k(a) g(b, c) H$ is a diffeomorphism from $\mathbb{R}^{3}$ to $K / H$, proving our claim.

Let $e_{4}=f$ and let $\theta=\theta^{i} e_{i}$ be the canonical form of $K$. (3.10) yields

$$
\begin{align*}
& \mathrm{d} \theta^{1}-\left(\theta^{2}+\theta^{3}\right) \wedge \theta^{4}=0 \\
& \mathrm{~d} \theta^{4}-\left(\Omega \theta^{1}-b \theta^{4}\right) \wedge\left(\theta^{2}+\theta^{3}\right)=0 \\
& \mathrm{~d} \theta^{2}+b \theta^{2} \wedge \theta^{3}+\theta^{1} \wedge \theta^{4}=0 \\
& \mathrm{~d} \theta^{3}-b \theta^{2} \wedge \theta^{3}-\theta^{1} \wedge \theta^{4}=0 \tag{3.13}
\end{align*}
$$

with the global solution

$$
\begin{align*}
& \theta^{2}=\exp (b x)(\beta u \cdot \mathrm{~d} v+\mathrm{d} t) \\
& \theta^{2}+\theta^{3}=\mathrm{d} x  \tag{3.14}\\
& \left(-\frac{1}{2} b+\mathrm{i} \beta\right) \theta^{1}+\theta^{4}=\beta \exp \left(\frac{1}{2} b+\mathrm{i} \beta\right) x \cdot(\mathrm{~d} u+\mathrm{i} \mathrm{~d} v)
\end{align*}
$$

The Pfaffian system $\theta^{1}=\theta^{2}=\theta^{3}=0$ has the first integrals $x, y, z$, where

$$
\begin{equation*}
y=v+u \tan (\beta x), \quad z=-\frac{1}{2} \beta u^{2} \tan (\beta X)+t \tag{3.15}
\end{equation*}
$$

Then, on $K$ the projectable tensor

$$
g=\left(\theta^{1}\right)^{2}+\left(2 \theta^{2}-\left(\theta^{2}+\theta^{3}\right)\right)\left(\theta^{2}+\theta^{3}\right)
$$

is given by (3.12).
Remarks. The Lorentz spaces in Propositions 3.2, 3.3, are locally the only possible three-dimensional nonsymmetric homogeneous spaces modelled on a symmetric space. Together with the lists in Refs. [6,] or [18], they give the full picture of the local metric structures of homogeneous Lorentz three-dimensional manifolds.

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